

Vector.di

Background



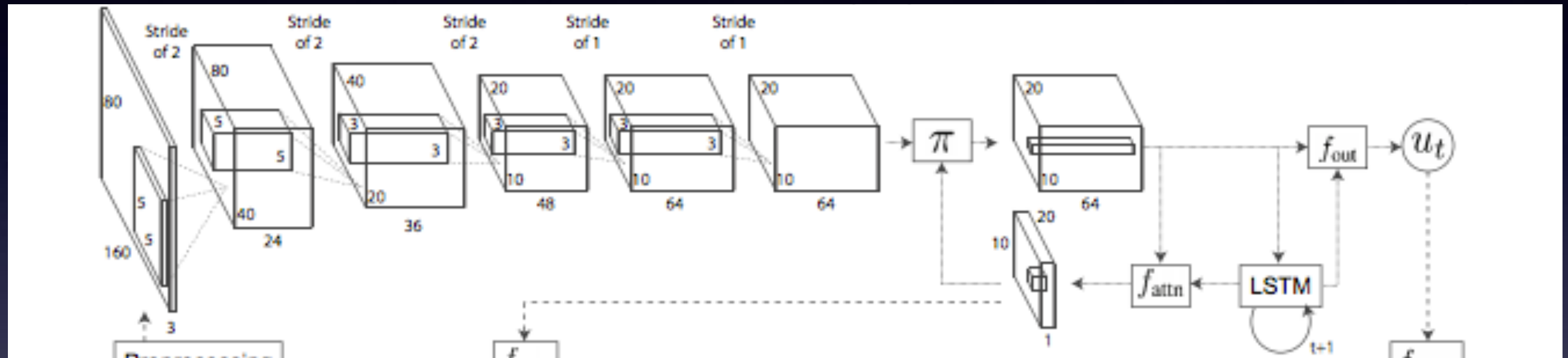
Start From Zero



Get the Control quickly



LSTM and Segmentation

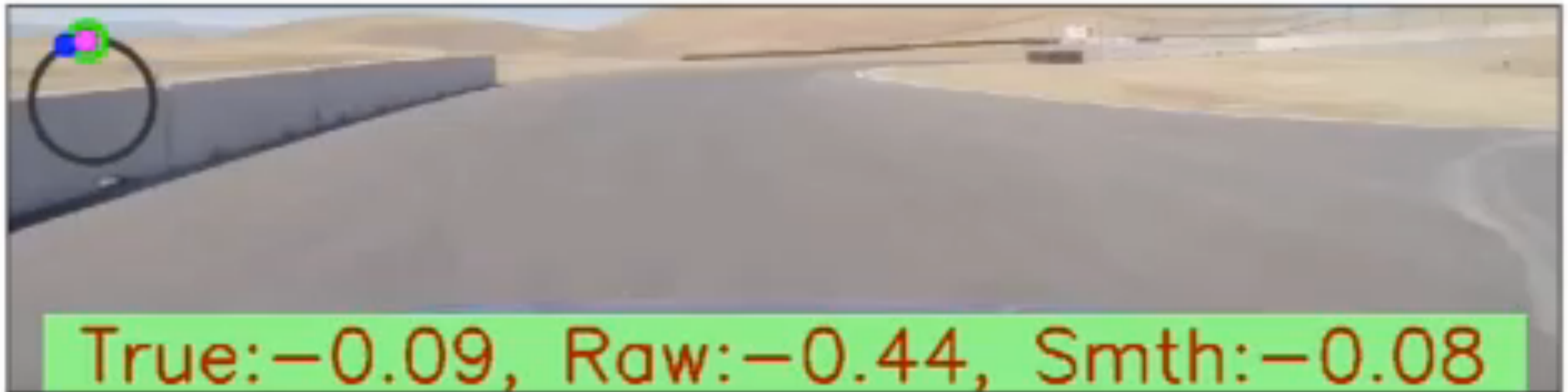


Encoder

Coarse Grained Decoder

Fine Grained Decoder

Result



Begin Testing



Two Known Approaches to Develop Self-Driving Car



Robotics/ DARPA

Why don't we have both ?
Deep Learning and Robotics



Deep Learning Approach

Self-Driving Car Matrix

Software

TensorRT



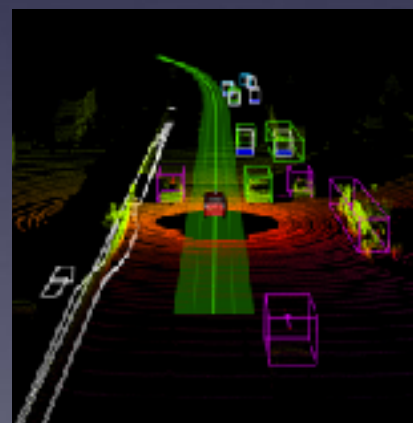
Computer Vision



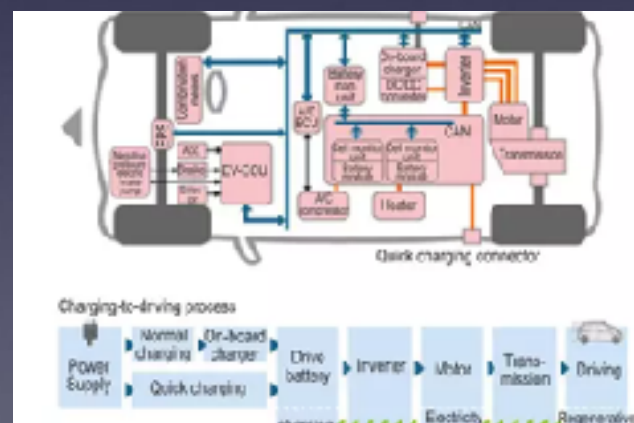
Infrastructure



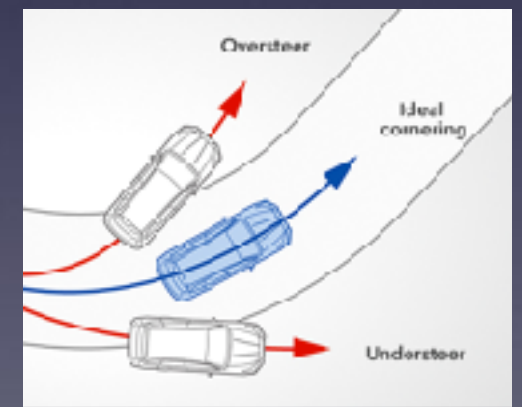
Hardware



Sensor Fusion



Vehicle Networks

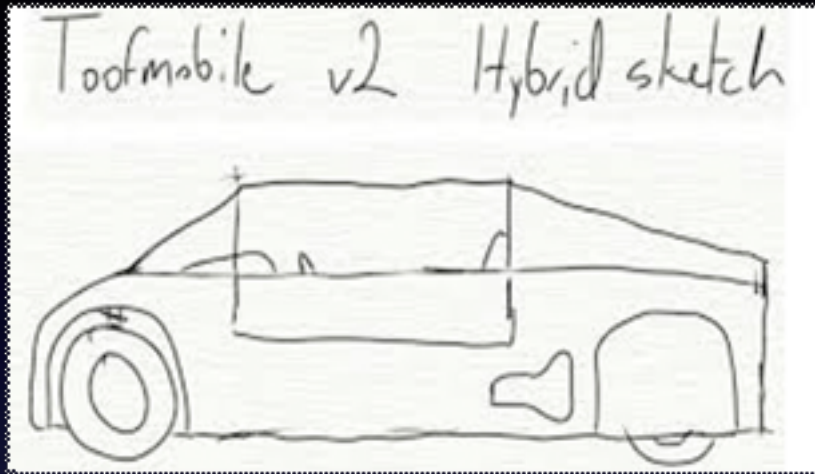


Vehicle Dynamics

What kind of work ?



What OE's think I do



What my parents think I do



What friends think I do



What the government think I do



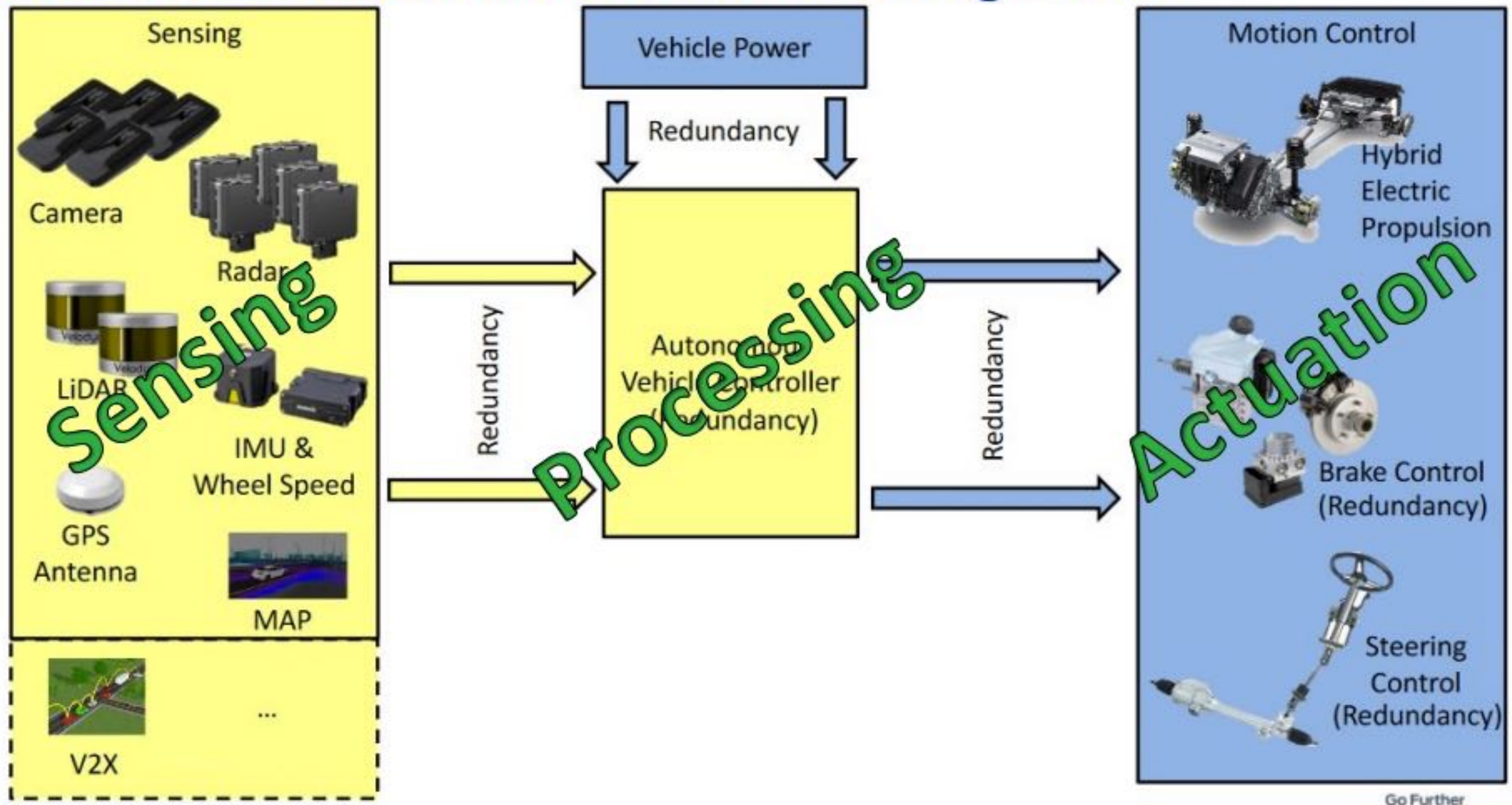
What I think I do



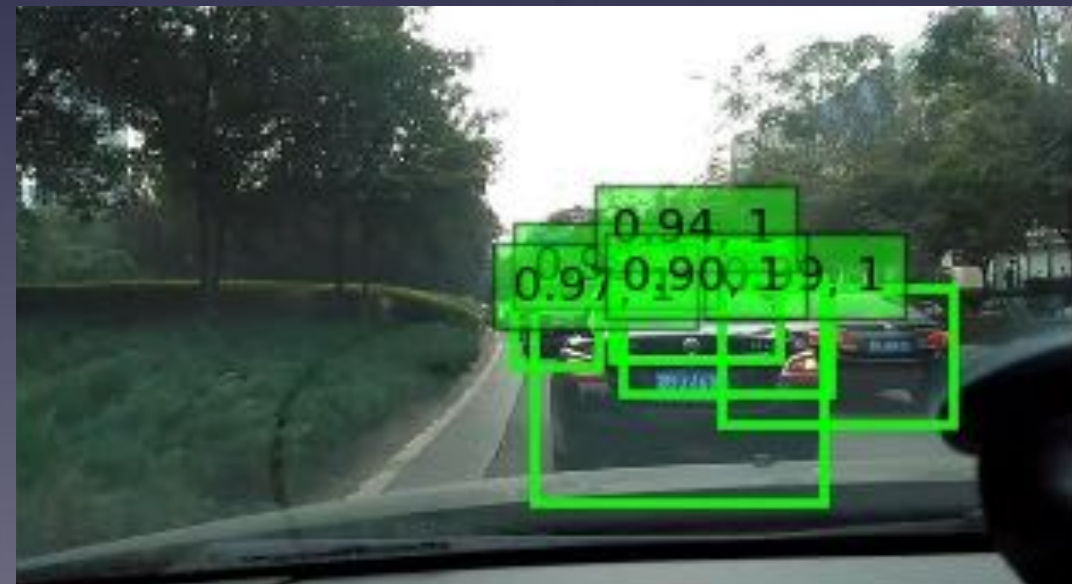
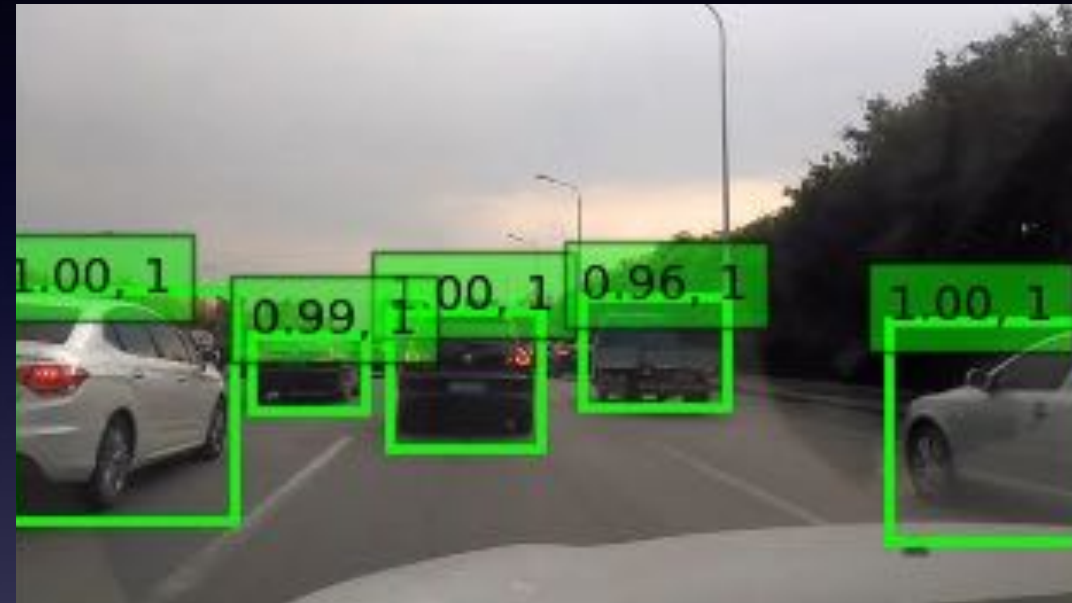
What I actually do

Needs in Autonomous Driving

Ford Level 4 Autonomous Vehicle Configuration



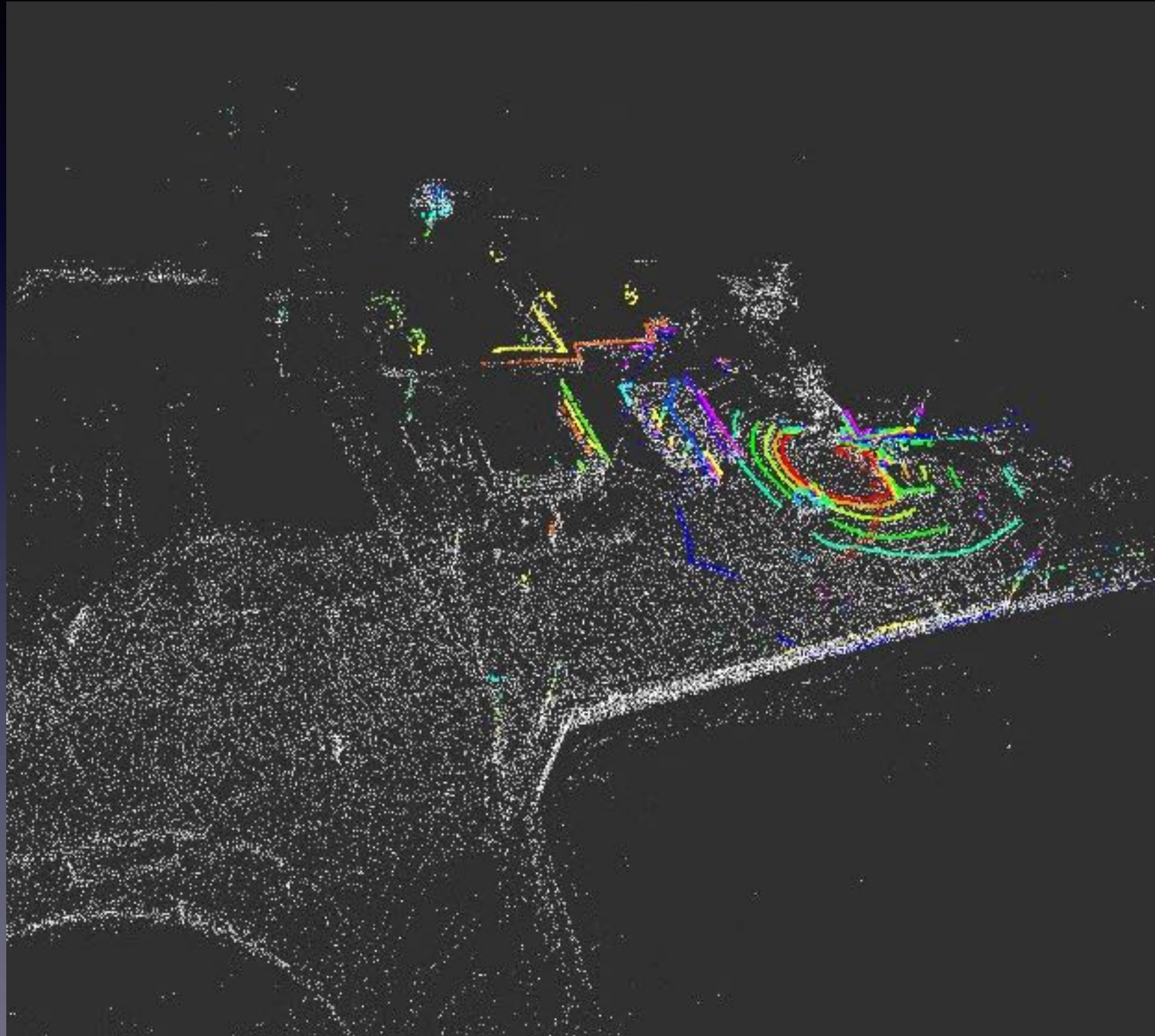
Hello China Traffic @ 30 fps



Learning Driving Behavior



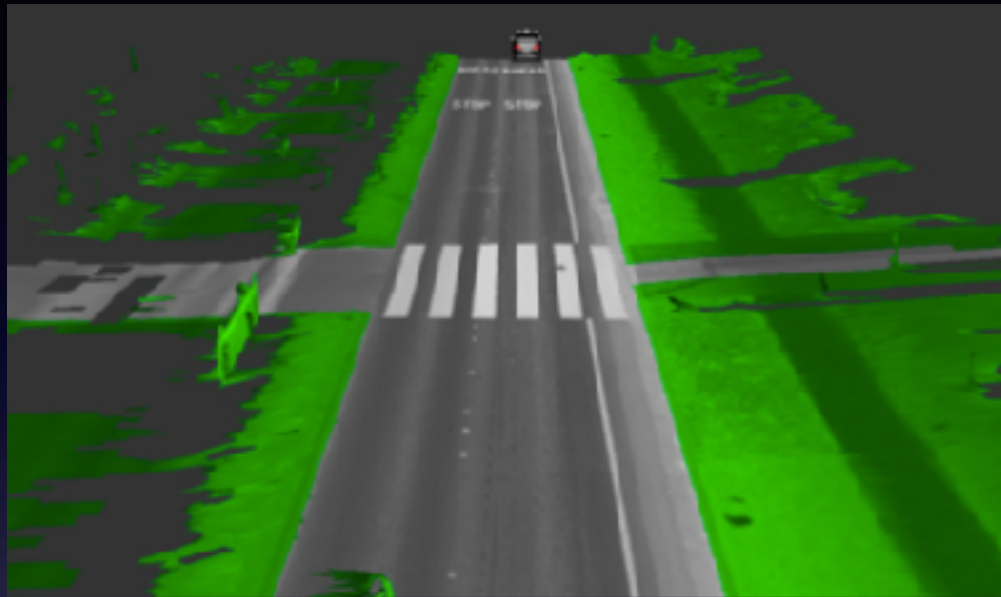
DeepSLAM The World !



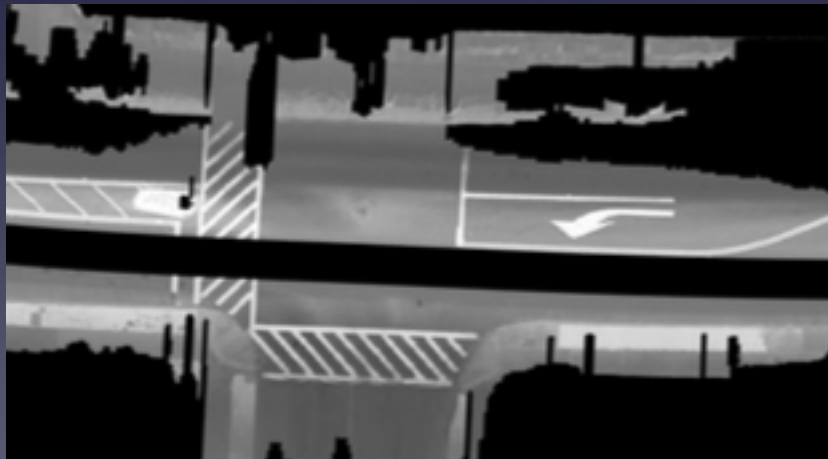
CNN/RNN/LSTM tested on RC Car



Testing back again on the Road



Feature extraction from
Velodyne for Ground Plane



Sunny Day



Heavy Rain Night

SLAM
Optimization

Road Testing



2017 Autonomous Lap



Thanks!